## How to Use Fortran Compiler for Vector Engine

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In this document, "parallel processing" stands for automatic parallelization of compiler or shared memory parallel processing with OpenMP Fortran.

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## NEC Fortran Compiler for Vector Engine

| Product Name: NEC Fortran Compiler for Vector Engine

- Conformed Language Standards
-ISO/IEC 1539-1:2004 Programming languages - Fortran
-ISO/IEC 1539-1:2010 Programming languages - Fortran (Partially)
- OpenMP Version 4.5
- Major Features
- Automatic Vectorization
- Automatic Parallelization and OpenMP Fortran
- Automatic Inline Expansion


## How to Use Fortran Compiler

## Usage of Fortran Compiler

```
$ nfort -mparallel -03 a.f90 b.f90
... Compile and link Fortran program(a.f90 b.f90)
```

| -04 | ... Automatic vectorization with the highest level optimization |
| :--- | :--- | :--- |
| -03 | .. Automatic vectorization with high level optimization |
| -02 | .. Automatic vectorization with default level optimization |
| -01 | ... Automatic vectorization with optimization without side-effects |
| -00 | ... No vectorization and optimization |

Parallelization controlling options.
Do not specify these options when you do not use shared memory parallelization.

## Example of Typical Compiler Option Specification

```
$ nfort a.f90
$ nfort -04 a.f90 b.f90
$ nfort -mparallel -03 a.f90
$ nfort -04 -finline-functions a.f90
$ nfort -00 -g a.f90
$ nfort -g a.f90
$ nfort -E a.f90
$ nfort -fsyntax-only a.f90
```

Compiling and linking with the default vectorization and optimization.

Compiling and linking with the highest vectorization and optimization.

Compiling and linking using automatic parallelization with the advanced vectorization and optimization.

Compiling and linking using automatic inlining with the highest vectorization and optimization.

Compiling and linking with generating debugging information in DWARF without vectorization and optimization.

Compiling and linking with generating debugging information in DWARF with the default vectorization and optimization.

Performing preprocessing only and outputting the preprocessed text to the standard output.

Performing only grammar analysis.

## Program Execution

```
$ nfort a.f90 b.f90
$ ./a.out
```

\$ ./b.out data1.in

Executing a program getting input file and parameter from command line.

```
$ ./c.out < data2.in
```

Executing with redirecting an input file instead of standard input file.

```
$ nfort -mparallel -03 a.f90 b.f90
$ export OMP_NUM_THREADS=4
$ ./a.out
```

\$ env VE_NODE_NUMBER=1 ./a.out
Executing with number of VE.

## Performance Analysis

## Performance Information of Vector Engine

## | PROGINF

- Performance information of the whole program.
- The overhead to get performance information is slightly.
- FTRACE
- Performance information of each function.
- It is necessary to re-compile and re-link the program.
- If functions are called many times, the overhead to get performance information and the execution time may increase.


## PROGINF

## Performance information of the whole program

```
$ nfort -04 a.f90 b.f90 c.f90
$ ls a.out
a.out
$ export VE_PROGINF=DETAIL
$ ./a.out
    ******** Program Information ********
    Real Time (sec) : 11.329254
User Time (sec) : 11.323691
Vector Time (sec) : 11.012581
Inst. Count
V. Inst. Count
V. Element Count
V. Load Element Count
FLOP count
MOPS
MOPS (Real)
MFLOPS
MFLOPS (Real)
A. V. Length
V. Op. Ratio (%)
L1 Cache Miss (sec)
CPU Port Conf. (sec)
V. Arith. Exec. (sec)
V. Load Exec. (sec)
VLD LLC Hit Element Ratio (%)
Power Throttling (sec)
Thermal Throttling (sec)
Max Active Threads
Available CPU Cores : 8
Average CPU Cores Used : 0.999509
Memory Size Used (MB)
    204.000000
```


## Set the environment variable

 "VE_PROGINF" to "YES" or "DETAIL" and run the executable file."YES" ... Basic information.
"DETAIL" ... Basic and memory information.

Time information
6206113403
2653887022
619700067996
53789940198
576929115066
73492.138481
73417.293683
50976.512081
50924.597321
233.506575
99.572922
0.010847
0.000000
8.406444
1.384491
100.000000
0.000000
0.000000

1
8
204.000000

## FTRACE

## Performance information of each function

```
$ nfort -ftrace a.f90 b.f90 c.f90 (Compile and link a program with -ftrace)
$ ./a.out
$ ls ftrace.out
ftrace.out
$ ftrace
*---------------------*
    FTRACE ANALYSIS LIST
*----------------------*
Execution Date : Thu Mar 22 17:32:54 2018 JST
Total CPU Time : 0:00'11"163 (11.163 sec.)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline FREQUENCY & \begin{tabular}{l}
EXCLUSIVE \\
TIME[sec]( \% )
\end{tabular} & \begin{tabular}{l}
AVER.TIME \\
[msec]
\end{tabular} & MOPS & MFLOPS & \[
\begin{aligned}
& \text { V.OP } \\
& \text { RATIO }
\end{aligned}
\] & \begin{tabular}{l}
AVER. \\
V.LEN
\end{tabular} & \begin{tabular}{l}
VECTOR \\
TIME
\end{tabular} & L1CACHE MISS & CPU PORT CONF & \begin{tabular}{l}
VLD LLC \\
HIT E.\%
\end{tabular} & PROC.NAME \\
\hline 15000 & 4.762( 42.7) & 0.317 & 77117.2 & 62034.6 & 99.45 & 251.0 & 4.605 & 0.002 & 0.000 & 100.00 & funcA \\
\hline 15000 & 3.541( 31.7) & 0.236 & 73510.3 & 56944.5 & 99.46 & 216.0 & 3.554 & 0.000 & 0.000 & 100.00 & funcB \\
\hline 15000 & 2.726( 24.4) & 0.182 & 71930.2 & 27556.5 & 99.43 & 230.8 & 2.725 & 0.000 & 0.000 & 100.00 & funcC \\
\hline 1 & 0.134( 1.2) & 133.700 & 60368.8 & 35641.2 & 98.53 & 214.9 & 0.118 & 0.000 & 0.000 & 0.00 & main \\
\hline 45001 & 11.163(100.0) & 0.248 & 74505.7 & 51683.9 & 99.44 & 233.5 & 11.002 & 0.002 & 0.000 & 100.00 & total \\
\hline
\end{tabular}
```

For an MPI program, multiple ftrace.out files are generated. Specify them by -f option.

```
$ ls ftrace.out.*
ftrace.out.0.0 ftrace.out.0.1 ftrace.out.0.2 ftrace.out.0.3
$ ftrace -f ftrace.out.0.0 ftrace.out.0.1 ftrace.out.0.2 ftrace.out.0.3
```


## Notes of Performance Analysis

In FTRACE, performance information is collected at the function entry/exit. So if many functions are called, the execution time would increase.

```
$ nfort -ftrace -c a.f90
$ nfort -c main.cpp b.f90 c.f90
$ nfort -ftrace a.o main.o b.o c.o
$ ./a.out
```

- Compile with "-ftrace" only the file contains the target function.
- Also specify "-ftrace" for linking.
| Performance information of functions in the files compiled without -ftrace are contained in that of the caller function.

In FTRACE, performance information of the inlined functions are contained in that of the caller function.
| Performance information of system library functions

- PROGINF result contains the performance information of system library functions called from a program.
- FTRACE result contains the performance information of system library functions called from a program. They are included in the performance information of the caller function.


## Debugging

## Traceback Information

Compile and link with -traceback.
Set the environment variable "VE_TRACEBACK" to "FULL" or "ALL" at execution.

Set the environment variable "VE_FPE_ENABLE" to catch arithmetic exceptions.

| "DIV" | ... Divide-by-zero exception |
| :--- | :--- |
| "INV" | ... Invalid operation exception |
| "DIV, INV" | ... Both exceptions |

    "INV" ... Invalid operation exception
    "DIV,INV" ... Both exceptions
    | PROGRAM MAIN |
| :--- |
| REAL $:: ~ A, ~ B$ |
| A $=1.0$ |
| B $=0.0$ |
| PRINT $*, A / B$ |
| END |

Note: "VE_FPE_ENABLE" can be set to
any other value but traceback basically
uses "DIV" or "INV".

| $\$$ nfort -traceback main.f90 |  |
| :--- | :--- |
| $\$$ export VE_TRACEBACK=FULL |  |
| $\$$ export VE_ADVACEOFFYES |  |
| $\$$ export VE_FPE_ENABLE=DIV |  |
| $\$$./a.out |  |
| Runtime Error: Divide by zero at $0 \times 6000000105 d \theta$ |  |
| [ 1] Called from 0x600000010750 |  |
| [ 2] Called from 0x7f8f41e307a8 |  |
| [ 3] Called from 0x600000003700 |  |
| Floating point exception |  |
| $\$$ naddr2line -e a.out -a 0x6000000105d0 |  |
| 0x00006000000105d0 |  |
| l.../main.f90:5 |  |

Compile and link with -traceback
Use traceback information
Advance-mode is off
Catch exception of "divide-by-zero"

Traceback information

## Using GDB

Specify -g to the files including the functions which you want to debug, in order to minimize performance degradation

```
$ nfort -00 -g -c a.f90 < Only a.f90 is compiled with -00 -g(avoid performance degradation)
$ nfort -04 -c b.f90 c.f90 «~ The others are compiled without -g
$ nfort a.o b.o c.o
$ gdb a.out < < Run GDB
(gdb) break sub
Breakpoint 1 at sub
(gdb) run
Breakpoint 1 at sub
(gdb) continue
```

- When debugging without -00, compiler optimization may delete or move code or variables, so the debugger may not be able to reference variables or set breakpoints.
- The exception occurrence point output by traceback information can be incorrect by the advance control of HW. The advance control can be stopped to set the environment variable VE_ADVANCEOFF=YES. But the execution time may increase substantially to stop the advance control. Please take care it.


## Strace: Trace of System Call

```
$ /opt/nec/ve/bin/strace ./a.out
write(2, "delt=0.0251953, TSTEP".., 27) = 27
open("MULNET.DAT", O_WRONLY|O_CREAT|O_TRUNC, 0666)= 5
ioctl(5, TCGETA, 0x8000000CC0) Err#25 ENOTTY
fxstat(5, 0x8000000AB0)
write(5, "1 2 66 65", 4095) = 4095
write(5, "343 342", 4096) = 4096
write(5, "603 602", 4096) = 4096
write(5, "863 862", 4094) = 4094
write(5, "1105 1104", 4095) = 4095
write(5, "1249 1313 1312", 4095) = 4095
write(5, "1456 1457 1521 1520", 4095) = 4095
write(5, "1727", 4095) = 4095
```

...

## System call arguments

System call return values
-Arguments and return values of system calls are output - You can check if the system library has been called properly. - You should carefully select system calls to be traced by -e of strace, because the output would be so many.

## Automatic Vectorization

## Vectorization Features

| An orderly arranged scalar data sequence such as a line, column, or diagonal of a matrix is called vector data. Vectorization is the replacement of scalar instructions with vector instructions.

## Execution image of scalar instructions

$A(1)=B(1)+C(1)$
$A(2)=B(2)+C(2)$
$A(3)=B(3)+C(3)$
...
$A(100)=B(100)+C(100)$
$A(100)=B(100)+C(100)$
Execute one calculation 100 times

Execution image of scalar instructions

DO $I=1,100$
END DO

| $A(1)$ |
| :--- |
| $A(2)$ |
| $\ldots$ |
| $A(100)$ |$=$| $B(1)$ |
| :---: |
| $B(2)$ |
| $\ldots(100)$ |$+$| $C(1)$ |
| :---: |
| $C(2)$ |
| $\ldots$ |
| $C(100)$ |

Execute 100 calculation at once

At most 256 calculation at once

## Comparison of HW Instruction



$$
\text { Array "A" } \begin{array}{|c}
2,4 \ldots 200
\end{array}
$$

## Comparison of Instruction Execution Time

## Execution image of scalar addition instruction

 (when two instructions are simultaneously executed)$$
\begin{aligned}
& B(1)+C(1) \\
& E(1)+F(1)
\end{aligned}
$$



```
DO I = 1, 100
    A(I) = B(I) + C(I)
    D(I) = E(I) + F(I)
END DO
```

$$
B(100)+C(100)
$$

Scalar instruction
Vector instruction

$$
E(100)+F(100)
$$

Execution time


## Execution image of vector addition instruction

## Vectorizable Loop

- A loop which contains only vectorizable types and operations.
- Not include 1-byte, 2-byte and 16-byte data types.
-These types are rarely used in numerical calculations.
-There are no corresponding type of vector operation instructions.
- Not include function call.
- Except trigonometric functions, exponential functions and logarithmic functions. These are vectorizable.
| There are no unvectorizable dependencies in the definition and reference of arrays and variables.
- It is possible to change the calculation order.

【 Performance improvement can be expected by vectorization.

- Loop length (number of loop iterations) is sufficiently large.


## Unvectorizable Dependencies (1)

## The calculation order cannot be changed, when array elements or variables which defined in the previous iteration are referred in the later iteration.

Example 1
$D O I=2, N$
$A(I+1)=A(I) * B(I)+C(I)$
$E N D D O$
Unvectorizable, because the updated
" $A$ " value cannot be referenced.

Calculation order in scalar

| * $B(2)+C(2)$ | $A(3)=A(2) * B(2)+C(2)$ |
| :---: | :---: |
| $A(4)=A(3) * B(3)+C(3) ;$ | $A(4)=A(3) * B(3)+C(3) ;$ |
| $A(5)=A(4) * B(4)+C(4) ;$ | $A(5)=A(4) * B(4)+C(4) ;$ |
| $(6)=A(5) * B(5)+C(5)$ | $A(6)=A(5) * B(5)+C(5)$ |
|  | before |

Calculation order in scalar

$$
\begin{aligned}
\mathrm{A}(1) & =\mathrm{A}(2) * \mathrm{~B}(2)+\mathrm{C}(2) ; \\
\mathrm{A}(2) & =\mathrm{A}(3) * \mathrm{~B}(3)+\mathrm{C}(3) ; \\
\mathrm{A}(3) & =\mathrm{A}(4) * \mathrm{~B}(4)+\mathrm{C}(4) ; \\
\mathrm{A}(4) & =\mathrm{A}(5) * \mathrm{~B}(5)+\mathrm{C}(5) ;
\end{aligned}
$$

Calculation order in vector

$$
\begin{aligned}
& \mathrm{A}(1)=\mathrm{A}(2) * \mathrm{~B}(2)+\mathrm{C}(2) ; \\
& \mathrm{A}(2)=\mathrm{A}(3) * \mathrm{~B}(3)+\mathrm{C}(3) ; \\
& \mathrm{A}(3)=\mathrm{A}(4) * \mathrm{~B}(4)+\mathrm{C}(4) ; \\
& \mathrm{A}(4)=\mathrm{A}(5) * \mathrm{~B}(5)+\mathrm{C}(5) ;
\end{aligned}
$$

Check that there is no lower right arrow between loop iterations.

## Unvectorizable Dependencies (2)

## Example 3

$$
\text { DO } \begin{aligned}
& I=1, N \\
& A(I)=S \\
& S=B(I)+C(I)
\end{aligned}
$$

END DO
Unvectorizable, because the reference of " S " appears before its definition in a loop.

Calculation order in scalar

$$
\begin{aligned}
& A(1)=S \\
& S=B(1)+C(1) \\
& A(1)=S \\
& S=B(1)+C(1)
\end{aligned}
$$

:

Calculation order in vector

$$
\begin{gathered}
A(1)=S \\
A(2)=S \\
: \\
A(N)=S \\
S=B(1)+C(1) \\
S=B(2)+C(2)
\end{gathered}
$$

Calculation order in scalar
Calculation order in vector

$$
\begin{aligned}
& A(1)=S \\
& S=B(1)+C(1) \\
& A(2)=S \\
& S=B(2)+C(2) \\
& :
\end{aligned}
$$

$$
\begin{aligned}
& A(1)=S \\
& S=B(1)+C(1) \\
& S=B(2)+C(2) \\
& \vdots \\
& A(2)=S \\
& A(3)=S
\end{aligned}
$$

## Unvectorizable Dependencies (3)

## Example 4

```
S = 1.0
DO I = 1, N
    IF (A(I) .LT. 0.0) THEN
        S = A(I)
    END IF
    B(I) = S + C(I)
    END DO
```


## Example 5

```
DO I = 1, N
    IF (A(I) .LT. 0.0) THEN
        S = A(I)
    ELSE
        S = D(I)
    END IF
    B(I) = S + C(I)
END DO
```


## Example 6

```
DO \(\mathrm{I}=1, \mathrm{~N}\)
    \(A(I)=A(I+K)+B(I)\)
END DO
```

Cannot be vectorized when a variable definition may not be executed, even if its definition precedes its reference.

Can be vectorized, because there is always a definition of " S " before its reference.

## Vectorization of Array Expression

Program

$$
\begin{aligned}
& A(1: M, 1: N)=B(1: M, 1: N)+C(1: M, 1: N) \\
& B(1: M, 1: N)=\operatorname{SIN}(D(1: M, 1: N))
\end{aligned}
$$

Image of transformation by compiler 2

```
DO J = 1, N
    DO I =1, M
        A(I,J) = B(I,J) + C(I,J)
        B(I,J) = SIN(D(I,J))
    END DO
END DO
```

Image of transformation by compiler 1

```
DO J = 1, N
    DO I =1, M
        A(I,J) = B(I,J) + C(I,J)
    END DO
END DO
DO J = 1, N
    DO I =1, M
        B(I,J) = SIN(D(I,J))
    END DO
END DO
END DO

An array expression is vectorized on optimal dimension after the compiler internally transforms it to DO loop format and performs optimizations such like loop fusion, loop collapse and so on.

\section*{Vectorization of IF Statement}

Conditional branches (IF statements) are also vectorized.
```

DO I = 1, 100
IF (A(I) .LT. B(I)) THEN
A(I) = B(I) +C(I)
END IF
END DO

```

\section*{Execute with vector operations}
```

mask(1) = A(1) .LT. B(1)
mask(2) = A(2) .LT. B(2)
: : :
mask(100) = A(100) .LT. B(100)

```
```

if (mask(1) ==.TRUE.) $\quad A(1)=B(1)+C(1)$
if $(\operatorname{mask}(2)==$. TRUE. $) \quad A(2)=B(2)+C(2)$
if $(\operatorname{mask}(100)==$. TRUE. $) \mathrm{A}(100)=\mathrm{B}(100)+\mathrm{C}(100)$

```

\section*{Diagnostic Message}

\section*{| You can check the vectorization status from output messages and lists of the compiler. \\ - Standard error \\ ... -fdiag-vector=2 (detail) \\ - Outputs diagnostic list ... -report-diagnostics}
```

\$ nfort -fdiag-vector=2 abc.f
nfort: vec( 103): abc.f, line 23: Unvectorized loop.
nfort: vec( 122): abc.f, line 24: Dependency unknown. Unvectorizable dependency is assumed.: RHO
nfort: vec( 122): abc.f, line 25: Dependency unknown. Unvectorizable dependency is assumed.: RHO
nfort: vec( 101): abc.f, line 50: Vectorized loop.
\$ nfort -report-diagnostics abc.f
\$ less abc.L
FILE NAME: abc.f

```

PROCEDURE NAME: SUB dIAGNOSTIC LIST

LINE
DIAGNOSTIC MESSAGE
```

23: vec( 103): Unvectorized loop.
24: vec( 122): Dependency unknown. Unvectorizable dependency is assumed.: RHO
25: vec( 122): Dependency unknown. Unvectorizable dependency is assumed.: RHO
50: vec( 101): Vectorized loop.

```

A message indicating that pointer RHO is considered to have a dependency that cannot be vectorized and has not been vectorized

\section*{Format List}
| Loop structure and vectorization, parallelization and inlining statuses are output with the source lines
- A format list is output when -report-format is specified.


The whole loop is vectorized.

The loop is not vectorized.

\section*{Extended Vectorization Features}

\section*{Extended Vectorization Features}

When the basic conditions for vectorization are not satisfied, the compiler performs as much vectorization as possible by transforming the program and using the special vector operations.
| Statement Replacement
| Loop Collapse
|Loop Interchange
| Partial Vectorization
- Conditional Vectorization
| Macro Operations
| Outer Loop Vectorization
|Loop Fusion
\| Inlining

\section*{Statement Replacement}

Source Program
\[
\begin{aligned}
& \text { DO } \begin{array}{l}
I=1,99 \\
A(I)=2.0 \\
B(I)=A(I+1)
\end{array} \\
& \text { END DO }
\end{aligned}
\]

When this loop is vectorized, all the value from \(B[1]\) to \(B[99]\) will be 2.0. This loop do not satisfy the vectorization conditions.

Transformation Image
```

DO I = 1, }9
B(I) = A(I+1)
A(I) = 2.0
END DO

```

The compiler replaces the statements in the loop to satisfy the vectorization conditions.

\section*{Loop Collapse}

Source Program
```

REAL A(M,N), B(M,N),C(M,N)
DO J = 1, N
DO I = 1, M
A(I,J)=B(I,J) +C(I,J)
END DO
END DO

```

Transformation Image
```

REAL A(M,N), B(M,N), C(M,N)
DO IJ = 1, M*N
A(IJ,1) = B(IJ,1) + C(IJ,1)
END DO

```

A loop collapse is effective in increasing the loop iteration count and improving the efficiency of vector instructions.

\section*{Loop Interchange}

Source Program
```

DO J = 1, M
DO I = 1, N
A(I+1,J) = A(I,J) + B(I,J)
END DO
END DO

```
\[
\begin{aligned}
& A(2,1)=A(1,1)+B(1,1) \\
& A(3,1)=A(2,1)+B(2,1) \\
& A(4,1)=A(3,1)+B(3,1) \\
& A(5,1)=A(4,1)+B(4,1)
\end{aligned}
\]

The loop "DO I=1,N" has unvectorizable dependency about the array A.

\section*{Transformation Image}
\[
\begin{aligned}
& \text { DO } I=1, N \\
& \text { DO } J=1, M \\
& \text { A(I+1,J) }=A(I, J)+B(I, J) \\
& \text { END DO } \\
& \text { END DO }
\end{aligned}
\]
\[
\begin{aligned}
& A(2,1)=A(1,1)+B(1,1) \\
& A(2,2)=A(1,2)+B(1,2) \\
& A(2,3)=A(1,3)+B(1,3) \\
& A(2,4)=A(1,4)+B(1,4)
\end{aligned}
\]

Interchanging loops removes unvectorizable dependency, and enable the loop " \(\mathrm{DO} \mathrm{J}=1, \mathrm{M}\) " to be vectorized.

\section*{Partial Vectorization}

Source Program
```

DO I = 1, N
X = A(I) + B(I)
Y = C(I) + D(I)
WRITE(6,*) X, Y
END DO

```

Transformation Image
```

DO I = 1, N
WX(I) = A(I) + B(I)
WY(I) = C(I) + D(I)
END DO
DO I = 1, N
WRITE(6,*) WX(I), WY(I)
END DO

```

If a vectorizable part and an unvectorizable part exist together in a loop, the compiler divides the loop into vectorizable and unvectorizable parts and vectorizes just the vectorizable part.
To do this, work vectors (the array WX and WY in above example) are generated if necessary.

\section*{Conditional Vectorization}

Source Program
```

DO I = N, N+99
A(I) = A(I+K) + B(I)
END DO

```

Transformation Image
```

IF((K.GE.0) .OR. (K.LT.-99)) THEN
! Vectorized Code
ELSE
! Unvectorized Code
END IF

```

The compiler generates a variety of codes for a loop, including vectorized codes and scalar codes, as well as special codes and normal codes. The type of code is selected by run-time testing at execution when conditional vectorization is performed.
```

(When $\mathrm{k}=-1$ )
$A(I)=A(I-1)+B(I)$

```
(When \(\mathrm{k}=-100\) )
    \(A(I)=A(I-100)+B(I)\)


\section*{Macro Operations}

Sum
```

DO I = 1, N
S=S + A(I)
END DO

```

Iteration
```

DO I = 1, N
A(I) = A(I-1) * B(I) + C(I)
END DO

```

Although patterns like these do not satisfy the vectorization conditions for definitions and references, the compiler recognizes them to be special patterns and performs vectorization by using proprietary vector instructions.

Maximum or minimum values
```

DO I = 1, N
IF (XMAX .LT. X(I)) THEN
XMAX = X(I)
END IF
END DO

```

\section*{Outer Loop Vectorization}

Source Program
```

DO I = 1, N
DO J = 1, N
A(I,J) = 0.0
END DO
B(I) = 1.0
END DO

```

Transformation Image
```

DO I = 1,N
DO J = 1,N
A(I,J) = 0.0
END DO
END DO
DO I = 1, N
B(I) = 1.0
END DO

```

In this case, these loops are collapsed.

The compiler basically vectorizes the innermost loop. If a statement which is contained only in the outer loop exists, the compiler divides the loop and vectorizes the divided outer loop.

\section*{Loop Fusion}

Source Program
```

DO I = 1, N
A(I) = B(I) + C(I)
END DO
DO I = 1, N
D(I) = SIN(E(I))
END DO

```
```

A(1:M) = B(1:M) + C(1:M)
D(1:M) = E(1:M) * F(1:M) + S

```

Transformation Image
```

DO I = 1, N
A(I) = B(I) +C(I)
D(I) = SIN(E(I))
END DO

```
```

DO I = 1, M
A(I,J) = B(I,J) + C(I,J)
D(I,J) = E(I,J)*F(I,J) +S
END DO

```

The compiler fuses consecutive loops which have the same iteration count and vectorizes the fused loop.
If the same shape array and loop structure are continuous, they can be fused. But if there are the different shape arrays, loop structures, and other sentences, they cannot be fused.
In order to increase speed, it is better to make same shape arrays and loop structures continuous as much as possible.

\section*{Vectorization with Inlining}

Source Program
```

DO I = 1, N
CALL SUB(B(I),C(I))
A(I) = B(I)
END DO
SUBROUTINE SUB(X,Y)
X = SIN(Y)
END

```

Transformation Image
```

DO I=1,N
B(I) = SIN(C(I))
A(I) = B(I)
END DO
SUBROUTINE SUB(X,Y)
X = SIN(Y)
END

```

When the -finline-functions option is specified, the compiler expands the function directory at the point of calling it if possible. If the function is called in a loop, the compiler tries to vectorize the loop after inlining the function.

\section*{Program Tuning}
"Tuning" is to increase executing speed of a program (reduce the execution time) by specifying compiler options and \#pragma directives. The performance of Vector Engine system can be derived at the maximum by tuning.

\section*{Point of View in Tuning}
| Raising the Vectorization Ratio
- The vectorization ratio is the ratio of the part processed by vector instructions in the whole program.
- The vectorization ratio can be improved by removing the cause of unvectorization.
- Increase the part processed by vector instructions.
- Improving Vector Instruction Efficiency
- Increase the amount of data processed by one vector instruction.
- Make the iteration count of a loop (loop length) as long as possible.
- Stop vectorization when the loop is so short.
- See p. 21 "Comparison of instruction execution time".

【 Improving Memory Access Efficiency
- Avoid using a list vector.

\section*{Vectorization Ratio}

IThe ratio of the part processed by vector instructions in whole program

Scalar execution

Vector execution

| The vector operation ratio is used instead of the vectorization ratio
Vector
\begin{tabular}{l} 
Veration \\
operation \\
ratio
\end{tabular}

\section*{Loop Iteration Count and Execution Time}
| To maximize the effect of vectorization, the loop iteration count should be made as long as possible
- Increase the amount of data processed by one vector instruction.


It is difficult to analyze iteration count for each loops.

\section*{Analyze \\ average vector length.}

> The average number of date processed by one vector instruction. The maximum number is 256 .

Crossover length
(= about 3)

\section*{Process of Tuning}
| Finding the function whose execution time is long, vector operation ratio is law and average vector length is short from the performance analysis information
-PROGINF
- Execution time, vector operation ratio and average vector length of the whole program.
- FTRACE
- Execution time, execution count, vector operation ratio and average vector length of each function.
| Finding unvectorized loops in the function from diagnostics for vectorization

- Improving vectorization by specifying compiler options and directives

\section*{PROGINF}

\section*{Output example}
\begin{tabular}{|c|c|}
\hline ******** Program Information & ******** \\
\hline Real Time (sec) & 11.336602 \\
\hline User Time (sec) & 11.330778 \\
\hline Vector Time (sec) & 11.018179 \\
\hline Inst. Count & 6206113403 \\
\hline V. Inst. Count & 2653887022 \\
\hline V. Element Count & 619700067996 \\
\hline V. Load Element Count & 53789940198 \\
\hline FLOP count & 576929115066 \\
\hline MOPS & 73455.206067 \\
\hline MOPS (Real) & 73370.001718 \\
\hline MFLOPS & 50950.894570 \\
\hline MFLOPS (Real) & 50891.794092 \\
\hline A. V. Length & 233.506575 \\
\hline V. Op. Ratio (\%) & 99.572922 \\
\hline L1 Cache Miss (sec) & 0.010855 \\
\hline CPU Port Conf. (sec) & 0.000000 \\
\hline V. Arith. Exec. (sec) & 8.410951 \\
\hline V. Load Exec. (sec) & 1.386046 \\
\hline VLD LLC Hit Element Ratio (\%) & 100.000000 \\
\hline Power Throttling (sec) & 0.000000 \\
\hline Thermal Throttling (sec) & 0.000000 \\
\hline Max Active Threads & 1 \\
\hline Available CPU Cores & 8 \\
\hline Average CPU Cores Used & 0.999486 \\
\hline Memory Size Used (MB) & 204.000000 \\
\hline
\end{tabular}

\section*{| A.V.Length (Average vector length)}
- Indicator of vector instruction efficiency.
- The longer, the better (Maximum length: 256).
- If this value is short, the iteration count of the vectorized loops is insufficient.
| V.Op.Ratio (Vector operation ratio)
- Ratio of data processed by vector instructions.
- The larger, the better (Maximum rate: 100).
- If this value is small, the number of vectorized loops is small or there are few loops in the program.

\section*{FTRACE}
| A feature used to obtain performance information of each function
\(\bullet\) Focus on V.OP.RATIO (Vector operation ratio) and AVER.V.LEN (Average vector length) as well as PROGINF, and analyze the performance of each function.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{13}{|l|}{*---------------------*
FTRACE ANALYSIS LIST} \\
\hline \begin{tabular}{l}
Execution \\
Total CPU
\end{tabular} & \begin{tabular}{l}
Date : Thu Mar 2 \\
Time : 0:00'11"1
\end{tabular} & \[
\begin{array}{r}
15: 47: 42 \\
3(11.168
\end{array}
\] & \[
\begin{aligned}
& 2018 \text { JST } \\
& \text { sec.) }
\end{aligned}
\] & & & & & & & & & \\
\hline FREQUENCY & \begin{tabular}{l}
EXCLUSIVE \\
TIME[sec]( \% )
\end{tabular} & \begin{tabular}{l}
AVER.TIME \\
[msec]
\end{tabular} & MOPS & MFLOPS & \[
\begin{aligned}
& \text { V.OP } \\
& \text { RATIO }
\end{aligned}
\] & \begin{tabular}{l}
AVER. \\
V.LEN
\end{tabular} & \[
\begin{array}{r}
\text { VECTOR } \\
\text { TIME }
\end{array}
\] & L1CACHE MISS & & PORT CONF & VLD LLC HIT E.\% & PROC.NAME \\
\hline 15000 & 4.767(42.7) & 0.318 & 77030.2 & 61964.6 & 99.45 & 251.0 & 4.610 & 0.002 & & 0.000 & 100.00 & FUNC_A \\
\hline 15000 & 3.541( 31.7) & 0.236 & 73505.6 & 56940.8 & 99.46 & 216.0 & 3.555 & 0.000 & & 0.000 & 100.00 & FUNC_B \\
\hline 15000 & 2.726( 24.4) & 0.182 & 71930.1 & 27556.5 & 99.43 & 230.8 & 2.725 & 0.000 & & 0.000 & 100.00 & FUNC_C \\
\hline 1 & 0.134( 1.2) & 133.700 & 60368.9 & 35641.3 & 98.53 & 214.9 & 0.118 & 0.000 & & 0.000 & 0.00 & MAIN \\
\hline 45001 & 11.168(100.0) & 0.248 & 74468.3 & 51657.9 & 99.44 & 233.5 & 11.008 & 0.002 & & 0.000 & 100.00 & total \\
\hline
\end{tabular}

\section*{Tuning Techniques}

\section*{Compiler Directives}
| The compiler directive is to give the compiler the information that it cannot obtain from source code analysis alone to further the effects of the vectorization and parallelization, writing !NEC\$.
-The compiler directive format is as follows.
```

!NEC\$ directive-name [clause] (free format / fixed format)
*NEC\$ directive-name [clause] (fixed format)
cNEC\$ directive-name [clause] (fixed format)

```
- Major vectorized compiler directives.
- VECTOR/NOVECTOR : Allows [Disallows] automatic vectorization of the following loop
-IVDEP : Regards the unknown dependency as vectorizable dependency during the automatic vectorization.
```

!NEC\$ IVDEP
DO I = 1, N
A(IX(I)) = A(IX(I)) + B(I)
END DO

```
- Specify the vectorization directive option just before the loop by delimiting with the specified space.
- It works only for the loop immediately after the directive.

\section*{Dealing with Unvectorizable Dependencies (1)}

\section*{Raising Vectorization} Ratio
```

nfort: vec( 103): a.f, line 16: Unvectorized loop.
nfort: vec( 113): a.f, line 16: Overhead of loop division is too large.
nfort: vec( 121): a.f, line 18: Unvectorizable dependency.

```

Such messages may be displayed to attempt partial vectorization.
```

Unvectorized Loop

```
DO \(I=1\), \(N\)
```

DO $I=1$, $N$

```
DO \(I=1\), \(N\)
        IF (X(I).LT.S) THEN
        IF (X(I).LT.S) THEN
        IF (X(I).LT.S) THEN
        \(T=X(I)\)
        \(T=X(I)\)
        \(T=X(I)\)
    ELSE IF (X(I).GE.S) THEN
    ELSE IF (X(I).GE.S) THEN
    ELSE IF (X(I).GE.S) THEN
        \(T=-X(I)\)
        \(T=-X(I)\)
        \(T=-X(I)\)
        END IF
        END IF
        END IF
    \(Y(I)=T\)
    \(Y(I)=T\)
    \(Y(I)=T\)
    END DO
```

```
    END DO
```

```
    END DO
```

```

It cannot be vectorized.
Because compiler cannot recognizes the variable " \(T\) " is defined or not.

Compiler cannot
recognizes sum
type macro
operation.
Unvectorized Loop

Unvectorized Loop
```

DO I = 1, N
IF (A(I).GT.0.0) THEN
S = S + B(I)
ELSE
S = S + C(I)
END IF
END DO

```

\section*{Vectorized Loop}

\section*{Vectorized Loop}
DO I = 1, N
DO I = 1, N
    IF (X(I).LT.S) THEN
    IF (X(I).LT.S) THEN
        \(T=X(I)\)
        \(T=X(I)\)
    ELSE
    ELSE
        \(T=-X(I)\)
        \(T=-X(I)\)
    END IF
    END IF
\(Y(I)=T\)
\(Y(I)=T\)

```

DO I = 1, N

```
DO I = 1, N
    IF (A(I).GT.0.0) THEN
    IF (A(I).GT.0.0) THEN
    T = B(I)
    T = B(I)
    ELSE
    ELSE
        T = C(I)
        T = C(I)
    END IF
    END IF
    S = S + T
    S = S + T
END DO
```

END DO

```

Modified so that variable "T" is always defined.

> Vectorization as a sum type macro operation.
<Diagnostic message after vectorization>
```

nfort: vec( 101): a.f, line 16: Vectorized loop.
nfort: vec( 126): a.f, line 22: Idiom detected.: Sum.

```

Sum type macro operation is vectorized using special HW instruction

\section*{Dealing with Unvectorizable Dependencies (2)}

\section*{Raising} Vectorization Ratio
```

nfort: vec( 103): dep.f90, line 5: Unvectorized loop.
nfort: vec( 122): dep.f90, line 6: Dependency unknown. Unvectorizable dependency is
assumed.: A

```
| Specify "IVDEP" if you know that there are no unvectorizable data dependencies in the loops, even when the compiler assumed that some unvectorizable dependencies exist.

Unvectorized Loop
```

SUBROUTINE SUB(A, B, C, N, K)
INTEGER I, N, K
REAL A(N), B(N), C(N)
DO I = 1, N
A(I+K) = A(I) + B(I)
END DO
END SUBROUTINE SUB

```
It is not vectorized because it is unknown
whether the pattern of \(A(I-1)=A(I)\) or
the pattern of \(A(I+1)=A(I)\)

\section*{Vectorized Loop}
```

SUBROUTINE SUB(A, B, C, N, K)
INTEGER I, N, K
REAL A(N), B(N), C(N)
!NEC\$ IVDEP
DO I = 1, N
A(I+K) = A(I) + B(I)
END DO
END SUBROUTINE SUB

```
When it is clear that the pattern is \(\mathrm{A}(\mathrm{I}-1)\)
= A(I), specify "IVDEP" to vectorize
<Diagnostic message after vectorization>
```

nfort: vec( 101): dep.f90, line 5: Vectorized loop.

```

\section*{Inlining: Improving of Vectorization}

\author{
Raising Vectorization
}
```

nfort: vec( 110): a.f90, line 4: Vectorization obstructive procedure reference.: FUN
nfort: vec( 103): a.f90, line 4: Unvectorized loop.
nfort: opt(1025): a.f90, line 5: Reference to this procedure inhibits optimization.: FUN

```
| When a function call prevents vectorization, above messages are output
- Try to inlining with specifying "-finline-functions" option
```

SUBROUTINE SUB(A, B, C, D, N)
INTEGER I, N
REAL A(N), B(N), C(N), D(N)
DO I=1, N ! Unvectorized
A(I) = FUN(B(I),C(I)) / D(I)
END DO
END
FUNCTION FUN(X, Y)
REAL X, Y
FUN = SQRT(X) * Y
END FUNCTION FUN

```
<Specifying compiler option >
```

\$ nfort -finline-functions a.f90

```
<Transformation Image>
```

DO I=1, N ! Vectorized
A(I)= SQRT(B(I))*C(I) / D(I)
END DO

```

SQRT is a vectorizable function, so it does not prevent vectorization.
```

nfort: vec( 101): func.f90, line 4: Vectorized loop.
nfort: inl(1222): func.f90, line 5: Inlined: FUN

```

\section*{A Loop Contains an Array with a Vector Subscript Expression}
```

nfort: vec( 101): a.f90, line 5: Vectorized loop.
nfort: vec( 126): a.f90, line 6: Idiom detected.: LIST VECTOR

```
\| Specifying IVDEP for the list vector further improve performance
- List vector is an array with a vector subscript expression.
- When the same list vector appears on both the left and right sides of an assignment operator, it cannot be vectorized because its dependency is unknown.
Vectorized Loop ("LIST_VECTOR" Directives)
!NEC\$ LIST_VECTOR
DO I = 1, N
A(IX(I)) = A(IX(I)) + B(I)
END DO

Vectorized Loop ("IVDEV" Directives)
```

!NEC\$ IVDEP
DO I = 1, N
A(IX(I)) = A(IX(I)) + B(I)
END DO

```

If LIST_VECTOR is specified, the loop can be vectorized.
If the same element of array " A " is not defined twice or more in the loop, in other words, if there are no duplicate values in "IX(I)", more efficient vector instructions can be generated by specifying IVDEP instead of LIST_VECTOR.
<Message after vectorization by IVDEP>
```

nfort: vec( 101): a.f90, line 5: Vectorized loop.

```

\section*{Outer Loop Unrolling}
| Outer loop unrolling will reduce the number of load and store operations in the inner loops.
- Unrolling the outer loop when there are multiple loop nests reduces the number of loads and stores that use only the inner loop's induction variable.
```

```
DO J = 1, N
```

```
DO J = 1, N
    DO I = 1, M
    DO I = 1, M
        A(I,J) = B(I,J) + C(I)
        A(I,J) = B(I,J) + C(I)
    END DO
    END DO
END DO
```

```
END DO
```

```
Insert OUTERLOOP_UNROLL(4) directive
!NEC \(\$\) OUTERLOOP_UNROLL(4)
DO J = 1, N
    DO \(I=1, M\)
        \(A(I, J)=B(I, J)+C(I)\)
    END DO
END DO

Program after unrolling the outer loop 4 times.
```

DO J = 1, N%3
DO I = 1, M
A(I,J) = B(I,J) + C(I)
END DO
END DO
DO J = N%3+1, N, 4

```
```

                        4 times vector operations can
                                be performed per one vector
                                load in array "C"
    DO I = 1, M
        A(I,J) = B(I,J) +C(I)
        A(I,J+1) = B(I,J+1) + C(I)
        A(I,J+2) = B(I,J+2) + C(I)
        A(I,J+3) = B(I,J+3) +C(I)
    END DO
    END DO

```

Specifying OUTERLOOP_UNROLL directive or -fouterloop-unroll option shortens the loop length of the outer loop (induction variable "I") and reduces the number of vector loads of the array "C".
<Message after outer loop unroll by OUTERLOOP_UNROLL directive>
```

nfort: opt(1592): a.f90, line 5: Outer loop unrolled inside inner loop.: J
nfort: vec( 101): a.f90, line 6: Vectorized loop.

```

\section*{Small Iteration Loop}
| When the iteration count is small, loop controlling expressions can be eliminated
- The iteration count <= 256 : A short-loop which does not have "terminate loop?" is generated.
- The iteration count \(\ll 256\) : The loop is expanded and loop controlling expressions are eliminated.


Short-Loop
(Iteration count <= 256)


\section*{Loop Expansion}
(Iteration count <<256)


\section*{Notes on Using Vectorization}

\section*{Level of Automatic Vectorization and Optimization Applied}
| The following vectorization and optimization are applied automatically when changing the level of automatic vectorization at "-04", "-03" and "-02"
\begin{tabular}{|l|c|c|c|}
\hline \multicolumn{2}{|c|}{ high } & \multicolumn{1}{l|}{ low } \\
\hline Applied vectorization and optimization & \(\mathbf{- 0 4}\) & \(\mathbf{- 0 3}\) & \(\mathbf{- 0 2}\) \\
\hline \begin{tabular}{l} 
Vectorization by condition vectorization \\
(-m[no-]vector-dependency-test)
\end{tabular} & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline \begin{tabular}{l} 
Vectorization by loop collapse, loop interchange and \\
transform matrix multiply loops into a vector matrix library \\
function call. \\
(-f[no-]loop-collapse, \\
-f[no-]loop-interchange, \\
-[nno-]matrix-multiply)
\end{tabular} & \(\bigcirc\) & \(\bigcirc\) & - \\
\hline \begin{tabular}{l} 
Disallows the compiler to assume that the object pointed-to- \\
by a named pointer are aliasing in vectorization. \\
(-fnamed-[no]alias)
\end{tabular} & \(\bigcirc\) & \(\bigcirc\) & - \\
\hline \begin{tabular}{l} 
Allows outer-loop unrolling \\
(-f[no-]outerloop-unroll) \()\)
\end{tabular} & \(\bigcirc\) & \(\bigcirc\) & - \\
\hline
\end{tabular}

Remark: Only the major options are listed, () is the compiler option when specifying separately.

\section*{Influence on Result by Vectorization}
| Results may differ within an error range with and without vectorization
- "Conversion of division to multiplication" or "reordering of operations" may cause "loss of trailing digits", "cancellation" and "rounding error".
- The vector versions of mathematical functions do not always use the same algorithms as the scalar versions.
- An integer iteration macro operation is vectorized by using a floating point instruction. So when the result exceeds 52 bits or when a floating overflow occurs, the result differs from that of scalar execution.
- When vector fusion product-sum operation (FMA) is used, since addition is performed without rounding up the integration result in the middle, the operation result may be different from when it is not used.
| If you care about the error range
- Specify the "NOVECTOR" directive. The loop is not vectorized.
- Specify the "NOFMA" directive. Vector fused-multiply-add instruction does not generated.
```

!NEC\$ NOVECTOR
DO I = 1, N
SUM = SUM + A(I)
END DO

```

\section*{The Bus Error Caused by Vectorization}
| It may occur because vector load/store for 8 bytes elements is executed for the array aligned in 4 bytes
- In the following example, sub.f90 is compiled with -fdefault-real=8. Therefore, the arrays " \(A\) " and " \(B\) " of type REAL are vector loaded/stored for 8 bytes elements.
- Vector load/store for 8 bytes elements requires an array aligned in 8 bytes. If the array is aligned in 4 bytes, the execution failed by the bus error for an invalid memory access.
```

PROGRAM MAIN

```
PROGRAM MAIN
main.f90
main.f90
    REAL :: A(512), B(512)
    REAL :: A(512), B(512)
    CALL SUB(A,B,512)
    CALL SUB(A,B,512)
END
```

END

```
```

```
SUBROUTINE SUB(A, B, N)
```

```
SUBROUTINE SUB(A, B, N)
sub.f90
sub.f90
    INTEGER :: N
    INTEGER :: N
    REAL :: A(N), B(N)
    REAL :: A(N), B(N)
    B = A
    B = A
!!!<---vectorized
```

!!!<---vectorized

```
```

END SUBROUTINE SUB

```
```

END SUBROUTINE SUB

```
```

\$ nfort -c main.f90
\$ nfort -c -fdefault-real=8 sub.f90
\$ nfort main.o sub.o
\$ ./a.out
Bus error

```
| Declare an array as 4 bytes data type explicitly or specify the NOVECTOR directive to the loop to stop vectorization

SUBROUTINE \(\operatorname{SUB}(A, B, N)\)
INTEGER \(:: N\)
REAL \(:: A(N), B(N)\)
!NEC\$ NOVECTOR
\begin{tabular}{ll}
\(B=A\) & Specify NOVECTOR \\
END SUBROUTINE SUB & directive.
\end{tabular}

\section*{Automatic Parallelization and OpenMP Fortran}

\section*{Automatic Parallelization Features}
- Split one job and execute it simultaneously in multiple threads
- Split loop iteration.
- Split a series of processing (a collection of sentences) in a program.


Serial execution

Example when loop iteration is split into four


\section*{Reduce the Elapsed Time by Parallelization}
| Reduce the elapsed time by parallelization
- Increase total CPU time due to overhead for parallel processing.

Elapsed time


\section*{Program Parallelization}
| Program to execute in parallel in multiple threads
- Select loops and statements and extract code that can be execute in parallel.
- Generate executable code to execute in parallel with automatic parallelization or OpenMP.

Example 1: Parallelization by automatic parallelization
SUBROUTINE SUB(A, N)
INTEGER \(:: N, I, J\)
REAL(KIND \(=8):: A(N), B(N)\)
REAL \((K I N D=8):: S U M=1.0\)
DO \(J=1, N\)
DO \(I=1, N\)
SUM \(=S U M+A[j]+B[I]\)
ENDDO
ENDDO
RETURN
END SUBROUTINE SUB

Specify "-mparallel" to enable automatic parallelization.
\$ nfort -mparallel a.f90
nfort: par(1801): a.f90, line 6: Parallel routine generated.: SUB\$1
nfort: par(1803): a.f90, line 6: Parallelized by "do".
nfort: vec( 101): a.f90, line 7: Vectorized loop.
Extract as another function to execute the loop in parallel.

Remark: Other part of loop is regarded as impossible to execute in parallel.

\section*{Parallelization Programming Available on Vector Engine}

\section*{OpenMP Fortran}
- The programmer selects a set of loops and statement blocks that can be executed in parallel, and specifies OpenMP directives indicating how to parallelize them.
- The compiler transforms the program based on the instruction and inserts a directives for parallel processing control.

\section*{| Automatic parallelization}
- The compiler selects loops and statement blocks that can be executed in parallel and transforms the program into parallel processing control.
- The compiler automatically performs all the work of loop detection and program modification and directives insertion of "Example 1" on the previous page.
\begin{tabular}{|l|c|c|c|c|}
\hline \multicolumn{1}{|c|}{ Programming method } & \begin{tabular}{l} 
Select loops / \\
blocks
\end{tabular} & Insert directives & \begin{tabular}{l} 
Program \\
modification
\end{tabular} & Difficulty \\
\hline \begin{tabular}{l} 
OpenMP Fortran \\
(-fopenmp)
\end{tabular} & O & O & - & High \\
\hline \begin{tabular}{l} 
Automatic parallelization \\
(-mparallel)
\end{tabular} & - & - & - & Low \\
\hline
\end{tabular}

O : Handwork is needed.
- : Handwork is not needed because the compiler automatically executes it.

Remark: At the time of tuning, even if it is a section of "-", Handwork may be needed.

\section*{OpenMP Parallelization}

\section*{OpenMP Fortran}
\$ nfort -fopenmp a.f90 b.f90 Specify "-fopenmp" also when linking
| International standards of directives and libraries for shared memory parallel processing
- "NEC Fortran Compiler for Vector Engine" supports some features up to "OpenMP Version 4.5".
| Programming method
- The programmer extracts a set of loops and statements that can be executed in parallel, and specifies OpenMP directives indicating how to parallelize them.
- The compiler modifies the program based on the instruction and inserts processing for parallel processing control.
- Compile and link with "-fopenmp".
| Feature
- Higher performance improvement than automatic parallelization is expected because the programmer can select and specify the parallelization part.
- Easy to program because the compiler performs program transformation involving extraction of parallelized part, barrier synchronization and shared attribute of variables.

\section*{Example: Writing in OpenMP Fortran}

\section*{Parallelize subroutine "SUB" of Example 1 with OpenMP Fortran}


\section*{| The OpenMP directives follows "!\$OMP" to specify the parallelization method.}


\section*{Terms}
| OpenMP thread
\(\bullet\) A unit of logical parallelism. Sometimes abbreviated as thread.
| Parallel region
- A collection of statements executed in parallel by multiple OpenMP threads.
- Serial region
- A collection of statements executed only by the master thread outside of a parallel region.
| Private
- Accessible from only one of the OpenMP threads that execute parallel regions.
- Shared
- Accessible by all OpenMP threads executing parallel regions.

\section*{OpenMP Directives}

\section*{Explain only frequently used items}

\section*{!\$OMP PARALLEL DO [scheduLe-clause] [NOWAIT]}

SCHEDULE(STATIC[,size]) ... SCHEDULE(STATIC) is default value
-Perform round-robin allocation and execution on OpenMP threads with size iterations grouped together.
- When the specification of size is omitted, the value obtained by dividing size by the number of threads is regarded as specified.
SCHEDULE (DYNAMIC[, size])
- Dynamically allocate and execute on OpenMP thread by grouping size iterations together.
-When the specification of size is omitted, it is assumed that 1 is specified.
SCHEDULE(RUNTIME)
-Execute according to the schedule method set in the environment variable
"OMP_SCHEDULE".
NOWAIT
-Do not perform implicit barrier synchronization at the end of parallel loop.

\section*{!\$OMP SINGLE}

Execute only on one OpenMP thread. Execute with the task, not necessarily the master thread that reached the directive finally.

\section*{!\$OMP CRITICAL}

Do not execute in multiple OpenMP threads at the same time (exclusive control).

\section*{Automatic Parallelization}

\section*{Automatic Parallelization}

\section*{In automatic parallelization, compiler does everything suggested in "Example: Writing in OpenMP Fortran".}
```

\$ nfort -mparallel a.f90 b.f90

```

Also specify -mparallel for linking.
【 Compile and link with -mparallel.
- Compiler finds and parallelizes parallelizable loops and statements.
- Automatically select loops without factors inhibiting parallelization.
- Automatically select outermost loops in multiple loops.
-Innermost loops should be increased speed with vectorization.
- Compiler directives to control automatic parallelization.
- Compiler directive format
!NEC\$ directive-option
- Major directive options
- CONCURRENT/NOCONCURRENT ... parallelize/not-parallelize a loop right after this.
- CNCALL ... parallelize a loop including procedure calls.

\section*{Control Automatic Parallelization with Directives}
\| NoCONCURRENT ... Do not parallelize a loop right after this directive.
```

CALL SUB(4) ! function call
-..
SUBROUTINE SUB(M)
INTEGER :: M
...
!NEC\$ NOCONCURRENT
DO J = 1, M ! M is small actually
DO I = 1, N
A(I) = B(J) / C(J)
ENDDO
ENDDO

```

Performance sometimes degrades when small loop is parallelized because overhead of parallelization accounts for much ratio of execution.


Stop parallelization by NOCONCURRENT

\section*{- CNCALL ... Parallelize a loop including function call.}
```

!NEC\$ CNCALL
DO I = 1, M
A(I) = FUNC(B(I), C(I))
ENDDO

```

Loops including a procedure call is not parallelized automatically because it is unknown if the procedure can be executed in parallel.

Parallelize by CNCALL when procedures can be parallelized.
(Programmer must ensure that procedures can be executed in parallel.)

\section*{Apply Both OpenMP and Automatic Parallelization}
\$ nfort -fopenmp -mparallel a.f90 b.f90
| Compile and link with both -fopenmp and -mparallel.
- Automatic parallelization is applied to the loops outside of OpenMP parallel regions.
- If you don't want to apply automatic parallelization to a routine containing OpenMP directives, specify -mno-parallel-omp-routine.


\section*{Behavior of Parallelized Program}

\section*{Execution Image of Program Parallelized with OpenMP}

\section*{When parallelized with OpenMP Master thread}


Note: VE does not support nested parallelism.

\section*{Execution Image of Automatically Parallelized Program}

(Solid line: Program execution, Dashed line: Waiting process)

\section*{Decide Number of Threads in OpenMP}
| Number of threads used in parallel process is decided by rules as follows.


Note: Even if you requested over 8 threads, the maximum number of threads is 8 , because the number of VE cores is 8 .

\section*{Tuning Parallelized Program}

\section*{Point of View in Tuning}

\section*{| Are there many parts executed in parallel?}
- Is the ratio of execution time of parallelizable part to elapse time of whole part executed in single small?
(Increase parallelized execution part/parallelized loop.)
| Is parallelized effectively?
- Is execution time of parallelized loop long enough? (Parallelize suitable loops.)
- Is parallelization overhead large? (Reduce overhead.)
- Are workloads of each thread uniform? (Consider process in loops.)


\section*{Tuning Flow}
1. Select loop/procedure targets of parallelization.
- Find procedures whose execution time is long according to information of PROGINF and FTRACE.
2. Increase parallelized part.
- Check if loops in procedures found in 1. is parallelizable, and add the directives and transform program to parallelize them.
3. Improve load balance.
- Adjust load balance to make workloads of each thread uniform according to PROGINF and FTRACE information.

Note: Vectorization should be done enough before parallelization.

\section*{Select Loops for Parallelization}

In automatic parallelization, correspond loops are selected and parallelized automatically.
| Loops without factors inhibiting parallelization
- Not parallelizable dependencies.
- Not parallelizable control flow.
- Procedure call like I/O procedures whose execution order must be ensured.
| Outermost loop in multiple loops
- Loops whose execution time is long.
- Consider to increase speed of innermost loops with vectorization.
```

DO J = 1, N
DO I = 1, M
A(I,J) = B(I,J) + C(I,J)
ENDDO
ENDDO

```


\section*{Not Parallelizable Dependencies}

\section*{| Loops where the same array element is defined and referred in different iterations.}

Define and refer the same array element
```

DO I = 1, N
A(I) = B(I+1)
B(I)}=C(I
ENDDO

```
\begin{tabular}{cccc} 
Iteration & \multicolumn{2}{c}{ Reference } & Definition \\
\hline
\end{tabular}

The order of definition and reference of \(\mathrm{B}(3)\) is undefined.
| Loops where the same scalar variable is defined and referred in different iterations.

Same scalar variable
```

DO I = 1, N
C(I) = I
I}=B(I
}

```
- Parallelizable if the variable is referred after definition.
- Sum/Product patterns are parallelizable by transforming program, directives and so on. (Compiler recognizes the patterns and parallelizes automatically in automatic parallelization.)

Variable defined under a condition is referred out of it.
```

DO J = 1, N
DO I = 1, M
IF (A(I,J) .GE. D ) THEN
T = A(I,J) - D
ENDIF
C(I,J) = T
ENDDO
ENDDO

```
- Variable \(\mathbf{T}\) is defined in IF branch. Defined value is referred in iterations.
- This case is not parallelizable even if the variable is referred after definition.

\section*{Not Parallelizable Control Flow}

\section*{| Jump from loops}
- Not parallelizable because iterations must not be executed after that when condition for jumping is true.
```

DO J = 1, N
DO I = 1, N
IF (A(I,J) < 0.0 ) GOTO 100
B(I,J) = SQRT(A(I,J))
ENDDO
ENDDO
100 CONTINUE

```

\section*{Add Directives to Promote Parallelization}
```

\$ nfort -mparallel -fdiag-parallel=2 a.f90 -c
nfort: vec( 103): a.f90, line 5: Unvectorized loop.

```
| Loops including a procedure call is not parallelized automatically because it is unknown if the procedure can be executed in parallel.
| If the procedure can be executed in parallel, specify the directive CNCALL to parallelize automatically the loop.
```

SUBROUTINE SUB(A, B, N)
INTEGER :: N, I
REAL :: A(N), B(N), C(N)
DO I = 1, N
C(I) = FUNC(A(I), B(I))
ENDDO
END

```
```

SUBROUTINE SUB(A, B, N)
INTEGER :: N, I
REAL :: A(N), B(N), C(N)
!NEC\$ CNCALL
DO I = 1, N
C(I) = FUNC(A(I), B(I))
ENDDO
END

```
```

\$ nfort -mparallel -fdiag-parallel=2 a.f90 -c
nfort: par(1801): a.f90, line 5: Parallel routine generated.: SUB\$1
nfort: par(1803): a.f90, line 5: Parallelized by "do".
nfort: vec( 103): a.f90, line 5: Unvectorized loop.

```

\section*{Forced Parallelization Directive}

Not parallelized in automatic parallelization.
| It is ensured that a correct result can be obtained even in parallel execution.
| Specify forced parallelization directive PARALLEL DO to parallelize.
- Enable to specify parallelization for loops and statement list.
- Compiler ignore data dependencies and parallelize them.

Programmer must ensure that the correct result can be obtained in parallel
execution.

Specify ATOMIC right before statements which need to be processed exclusively like sum and accumulation in forced parallelized loops.
```

SUBROUTINE SUB(A, B, N)

```
SUBROUTINE SUB(A, B, N)
    INTEGER :: N, I, J
    INTEGER :: N, I, J
    REAL :: A(N), B(N), X(N), WK(256)
    REAL :: A(N), B(N), X(N), WK(256)
    REAL :: SUM = 0.0
    REAL :: SUM = 0.0
    !NEC$ PARALLEL DO PRIVATE(WK)
    !NEC$ PARALLEL DO PRIVATE(WK)
    DO I = 1, N
    DO I = 1, N
        DO J = 1, N
        DO J = 1, N
            WK(I) = A(I) + B(J)
            WK(I) = A(I) + B(J)
        ENDDO
        ENDDO
        CALL SUB1(X(J),WK)
    !NEC$ ATOMIC
        SUM = SUM + X(J)
    ENDDO
END SUBROUTINE SUB
```


## Overhead of Parallelization

| Overhead: Increased execution time by parallelizing a program.

- Execution time of the process added by a programmer to parallelize a program.
- Increased time by transforming a program.
- Processing time of runtime libraries to control parallelization.
- Waiting time of exclusive control in system libraries.
- Waiting time for exclusive control in system library functions to update and refer system data.
-File I/O functions, MALLOC() and so on.
- Waiting time for barrier sync with other threads.


## Exclusive Control in System Libraries

| Exclusive control is executed to inhibit the other OpenMP threads from updating data used in whole program at the same time when they are referred or updated.

- File descriptor, management data of area allocated with MALLOC() and so on.

| Reduce procedure calls in system libraries.
- Put together MALLOC() as much as possible.
- Declare the data used in a procedure as local data to allocate them in stack.
- Read file contents, map them on memory and read required data from memory when there are enough available area in memory.


## Reduce Waiting Time for Barrier Sync (1)

In OpenMP, barrier sync is executed automatically at places as follows.

- End of parallel loop without NOWAIT clause.
- End of parallel loop with reduction clause.(*)
- Beginning of parallel region with COPYIN clause.(*)
- End of parallel region.(*)

In automatic parallelization, compiler makes implicit barrier sync properly.

In the cases (*), barrier sync cannot be omitted because of the mechanism of parallel process.
| Make workloads of each thread uniform. (Reduce waiting time) - SChedule (dynamic) clause is effective to make workloads of parallel loop uniform which changes in each iteration.

```
!$OMP DO SCHEDULE(STATIC )
DO J = 1, M
    DO I = 1, N
    ENDDO
ENDDO
```

```
!$OMP DO SCHEDULE( DYNAMIC )
DO J = 1, M
    DO I = 1, N
    ENDDO
ENDDO
```


## Reduce Waiting Time for Barrier Sync (2)

| Remove implicit barrier sync by combining parallel regions.
|Remove unnecessary barrier sync by specifying nowait clause.

- Compiler ignores NOWAIT clause if it is specified on barrier sync unable to be removed.



## Improve Load Balance (1)

| There is much waiting time at the end of a loop as follows because the workloads of each thread are not uniform.

When parallel loop is split to 4 and they are executed by 4 threads


Beginning of parallel loop

End of parallel loop
Barrier sync executed


```
```

!\$OMP DO

```
```

!\$OMP DO
$\square$

```
```

DO J = 1024, 1, -1

```
DO J = 1024, 1, -1
```

DO J = 1024, 1, -1
DO I = 1, J
DO I = 1, J
DO I = 1, J
ENDDO
ENDDO
ENDDO
ENDDO

```
    ENDDO
```

    ENDDO
    ```
Iteration of inner loop or calculation amount decreased as the iteration of parallelized loop goes forward.
```

    ...
    ```
    ...
```

    ...
        *
    ```
        *
```

        *
    ```

\section*{Improve load balance}

All calculation can be done in shorter time by making workloads of each thread uniform and reducing waiting time.

\section*{Improve Load Balance (2)}

Split parallel region into smaller parts and assign them to each thread to make their workloads uniform.

\section*{- OpenMP parallelization}
- Adjust parameter of SCHEDULE clause.
```

!\$OMP DO SCHEDULE(DYNAMIC,4)
DO J = 1024, 1, -1
DO I = 1, J
ENDDO
ENDDO

```
| Automatic parallelization
- Adjust parameter of SCHEDULE clause in CONCURRENT directive as well as OpenMP.
```

!NEC\$ CONCURRENT SCHEDULE(DYNAMIC,4)
DO J = 1024, 1, -1
DO I = 1, J
ENDDO
ENDDO

```


Enable to reduce gap by splitting the region smaller.


When SCHEDULE (DYNAMIC,4) is specified

Make the number of regions as less as possible because the more it increases, the more time it takes to control threads.

\section*{FTRACE}

\section*{| Load balance in procedures are shown in information for each thread.}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline REQUENCY & \multicolumn{2}{|l|}{EXCLUSIVE AVER.TIME} & MOPS & MFLOPS & \multicolumn{2}{|l|}{V.OP AVER. RATIO V.LEN} & \multicolumn{5}{|l|}{\begin{tabular}{l}
VECTOR L1CACHE CPU PORT VLD LLC PROC.NAME \\
TIME MISS CONF HIT E.\%
\end{tabular}} \\
\hline 60000 & 62.177(73.1) & 1.036 & 100641.4 & 79931.0 & 99.55 & 248.5 & 62.134 & 0.023 & 0.000 & 100.00 & SUBX\$1 \\
\hline 15000 & 4.467 ( 5.3) & 0.298 & 107076.2 & 83033.3 & 99.47 & 248.4 & 4.455 & 0.005 & 0.000 & 100.00 & -thread0 \\
\hline 15000 & 11.552( 13.6) & 0.770 & 104082.7 & 82404.6 & 99.54 & 248.5 & 11.542 & 0.006 & 0.000 & 100.00 & -thread1 \\
\hline 15000 & 19.000( 22.3) & 1.267 & 101390.4 & 80683.3 & 99.55 & 248.6 & 18.990 & 0.006 & 0.000 & 100.00 & -thread2 \\
\hline 15000 & 27.157( 31.9) & 1.810 & 97595.1 & 77842.2 & 99.56 & 248.6 & 27.147 & 0.006 & 0.000 & 100.00 & -thread3 \\
\hline 15000 & 22.711( 26.7) & 1.514 & 1426.9 & 0.0 & 0.00 & 0.0 & 0.000 & 0.015 & 0.000 & 0.00 & SUBX \\
\hline 79001 & 85.034(100.0) & 1.076 & 74062.7 & 58500.4 & 98.89 & 248.5 & 62.249 & 0.043 & 0.000 & 100.00 & total \\
\hline
\end{tabular}

Specify !NEC\$ CONCURRENT SCHEDULE(DYNAMIC, 4) right before the outermost loop
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline REQUENCY & \[
\begin{aligned}
& \text { EXCLUSIVE } \\
& \text { TIME }[\mathrm{sec}](\%)
\end{aligned}
\] & AVER.TIME [msec] & MOPS & MFLOPS & V.OP
RATIO & \begin{tabular}{l}
AVER. \\
V.LEN
\end{tabular} & \multicolumn{5}{|l|}{VECTOR L1CACHE CPU PORT VLD LLC PROC.NAME TIME MISS CONF HIT E.\%} \\
\hline 60000 & 66.872( 99.6) & 1.115 & 93599.2 & 74318.7 & 99.52 & 248.5 & 64.077 & 1.418 & 0.000 & 100.00 & SUBX\$1 \\
\hline 15000 & 16.766( 25.0) & 1.118 & 92992.0 & 73842.7 & 99.52 & 248.5 & 16.022 & 0.409 & 0.000 & 100.00 & -thread0 \\
\hline 15000 & 16.697( 24.9) & 1.113 & 91671.0 & 72790.7 & 99.52 & 248.5 & 16.000 & 0.397 & 0.000 & 100.00 & -thread1 \\
\hline 15000 & 16.714( 24.9) & 1.114 & 94854.7 & 75312.8 & 99.52 & 248.5 & 16.040 & 0.305 & 0.000 & 100.00 & -thread2 \\
\hline 15000 & 16.695( 24.9) & 1.113 & 94880.7 & 75329.6 & 99.51 & 248.5 & 16.014 & 0.307 & 0.000 & 100.00 & -thread3 \\
\hline 15000 & 0.129 ( 0.2) & 0.009 & 1284.5 & 0.1 & 0.00 & 0.0 & 0.000 & 0.010 & 0.000 & 0.00 & SUBX \\
\hline 79001 & 67.148(100.0) & 0.850 & 93334.5 & 74082.8 & 99.51 & 248.5 & 64.192 & 1.430 & 0.000 & 100.00 & total \\
\hline
\end{tabular}

Before :EXCLUSIVE TIME are ununiform for -thread0 to -thread3 of SUBX\$1.(Load imbalance) After :EXCLUSIVE TIME are uniform for each thread and that of SUBX is shorter (time for barrier sync and so on are reduced) although that of SUBX\$1 increases because of time to control threads.

\section*{Notes on Using Parallelization}

\section*{Allocated Area by ALLOCATE Statement}

\section*{Whether the areas allocated by ALLOCATE statement are shared or private is decided as follows. \\ - Are allocated arrays or pointers shared or private? \\ - Is process executed in parallel when the area is allocated?}
```

P,Q : shared
R,S : private
Parallel process
section

```
```

SUBROUTINE SUB()
REAL,ALLOCATABLE :: P(:), Q(:)
REAL,ALLOCATABLE :: R(:), S(:)

```
    ALLOCATE(P(16))
```

    ALLOCATE(P(16))
    !$OMP PARALLEL PRIVATE(R,S)
!$OMP PARALLEL PRIVATE(R,S)
!$OMP SINGLE
!$OMP SINGLE
ALLOCATE(Q(16))
ALLOCATE(Q(16))
!$OMP END SINGLE
!$OMP END SINGLE
!$OMP MASTER
!$OMP MASTER
ALLOCATE(R(16))
ALLOCATE(R(16))
!$OMP END MASTER
!$OMP END MASTER
ALLOCATE(S(16))
ALLOCATE(S(16))
!$OMP END PARALLEL
!$OMP END PARALLEL
END SUBROUTINE SUB

```
END SUBROUTINE SUB
```

$\operatorname{ALLOCATE}(\mathrm{P}(16))$ is executed once. P is shared, so all threads refer the same area.

ALLOCATE( $Q(16)$ ) is executed by one thread and only one area is allocated. Q is shared, so all threads refer the same area.
$\operatorname{ALLOCATE}(R(16))$ is executed by only master thread and only one area is allocated. $R$ is private, so $R$ is still unallocated in threads other than master thread.

ALLOCATE (S(16)) is executed by all threads and four areas are allocated. S is private, so each thread uses separate areas.

## Huge Local Array

| When huge local array is used in a parallel region, set the environment variable OMP_STACKSIZE to a value which is larger than the size of the array.

- OMP_STACKSIZE is an environment variable which sets the maximum stack size of threads other than master thread. If this is not set, the maximum stack size is 4MByte.
- If the size of array is exceeded the size of unused area on stack, the program is terminated abnormally.

| Memory |  |
| :---: | :---: |
| Stack area of thread \#3 | $\downarrow_{\downarrow}$ Size set by OMP_STACKSIZE |
| Stack area of thread \#2 | The maximum stack size is rounded to the page size which is a multiple of 64MB. So it can be used over the size specified by OMP_STACKSIZE. But when the used size is over the rounded size, it causes abnormal termination. <br> If the maximum size is set too large, the other area (heap and so on) becomes smaller. So it is better not to specify the larger size than you need. |
| Stack area of thread \#1 |  |
| $\ldots$ |  |
| Stack area of |  |

```
$ cat a.f90
PROGRAM MAIN
!$OMP PARALLEL
    CALL SUB()
!$OMP END PARALLEL
END PROGRAM
SUBROTINE SUB()
    REAL(KIND=8) :: X(16*1024*1024)
    REAL(KIND=8) :: Y(16*1024*1024)
...
END SUBROUTINE SUB
$ nfort -fopenmp a.f90
$ export OMP_STACKSIZE=384M
$ ./a.out
```


## Sum Operation

| Sum operation can be parallelized but the order of additions can be changed every time because the order of execution of each threads is not constant.(Execution order is not ensured. )

- Calculation result may differ in operation error range from it in serial execution, or may vary at every execution in parallel.

```
DO I = 1, 100
    SUM = SUM + X(I)
ENDDO
```


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